

09:00	Welcome and Introduction
09:10	<b>Frank Chongwoo Park</b> (Seoul National University) Title: Geometric Robot Learning: From Models to Representations
09:50	<b>Gregory S. Chirikjian</b> (National University of Singapore) Title: Perspectives on Screws and Wrenches, and More
10:30	Q&A and Discussion Round
<b>10:40</b>	<b>Spotlight Poster Teasers</b>
11:10	Coffee-Break - Poster Session
11:30	<b>Leo Dorst</b> (University of Amsterdam) Title:TBD / Topic: Introduction to Geometric Algebra and Projective geometric algebra
12:10	<b>Steven De Keninck</b> (Origami Digital LLC) Title: TBD / Topic: Applications of GA and PGA - Efficiency, IK, RTOS
12:50	Q&A and Discussion Round
<b>13:00</b>	<b>Lunch Break + Poster Session</b>
13:45	<b>Noémie Jaquier</b> (Karlsruhe Institute of Technology) Title: TBD
14:15	<b>Murilo M. Marinho</b> , (Tokyo University) Title: Using Dual Quaternion Algebra for Constrained Applications in Robots for Surgery, Science, and Space.
14:45	Q&A and Discussion Round
14:55	<b>Jon Selig</b> (London South Bank University) Title: Screw Systems and Their Classification
15:35	<b>Joan Lasenby</b> (Cambridge University) Title: TBD / Topic: Conformal Geometric Algebra
16:15	Q&A and Discussion Round
16:25	Coffee-Break - Poster Session
16:45	<b>Eduardo Bayro Corrochano</b> (CINVESTAV) Title: Robot Modelling, Nonlinear Control and Trajectory Generation using the Geometric Algebra Framework
17:15	<b>Andreas Mueller</b> (Johannes Kepler University Linz) Title: The Role of Representation for Modeling and Control of Floating-Base and Space Robots
17:45	Q&A and Discussion Round
<b>17:55</b>	<b>Best Paper Award</b>
18:00	Drinks and talks at Fox Bar West-End - Conf Center