

### HiWi

# **Technical Engineer for Parallel and Distributed Robot Learning System**

## Background

Recent advancement in foundation models for robotics has highlighted the data scarcity issue in robotics community. For this we built a large-scale robot experiment system. We are looking for an outstanding HiWi (part-time) student to serve as a technical engineer in the collective learning team. This HiWi position offers a unique opportunity to gain work experience in a globally visible research group and to work with cutting-edge robotic systems, in the field of large-scale robot experiments. You will work closely with the researchers to support system development and assisting experiment operations. The work requires 20 hours commitment per week.

### **Your Tasks**

- Technical support for robot experiments: mechanical design, 3D printing, fabricating metal parts, etc.
- automation solution for experiment processes: design automation solution creatively to automate object/tool mounting process and experiment setup.
- experiment assistant: support the researchers in experiment setup, reset, monitoring.
- Possible software engineering tasks, for example front end GUI design, data visualization, web design, database maintenance.

### Requirement

- Familiar with mechanical design, 3D modelling, CAD software such as SolidWorks
- Experience in 3D printing and/or other fabrication techniques
- Knowledge in experiment design methodology
- Be patient and meticulous
- Highly motivated, responsible
- Software engineering in any of C++, Python, Database, Web front-end design is a plus

#### Contact: Dr. Fan Wu

#### f.wu@tum.de

Lehrstuhl für Robotik und Systemintelligenz TUM School of Computation, Information and Technology Technische Universität München